# Sprint review 3

We came together to review our progress over the last sprint (sprint 3) and set a goal for next sprint (sprint 4) which is also the last sprint so the end of this project.

## The meeting

There was no real feedback, just some tips on where to find information which might be useful. We did have some subjects that we wanted to finish before the end of this sprint, the main goals were having a connection between the PLC and the Unity digital environment, having a connection between the PLC and the Igus robot arm and to be able to control the digital environment while running.

We proved that we achieved these goals by showing some prove of concepts, these can next sprint be limed together into one working system. The conveyor belt can be adjusted during runtime and the conveyor system can also set information about the objects on the conveyor belt into the PLC.

On the other side, the PLC has communication with the Robot Arm and now will have to make it move, since the PLC can receive information about the objects the next step is to send this information to the Robot.

## The sprint

I think over all the time it took to finish the smaller pieces of the project where within or on the time stamp we predicted this semester. Obviously, we have had some problems in the sprint before so to project has changed and moved a little. Either way the sprint went pretty smooth and we all knew what to do to get as far as possible.

We all had a great feeling about this sprint since we have made some good progress and achieved what we wanted to achieve. The road ahead has also been more clear than ever so we are well motivated to also achieve our goals in the next sprint.

Afbeelding met tekst, schermopname, diagram, Perceel

Automatisch gegenereerde beschrijving